

FIG. 1

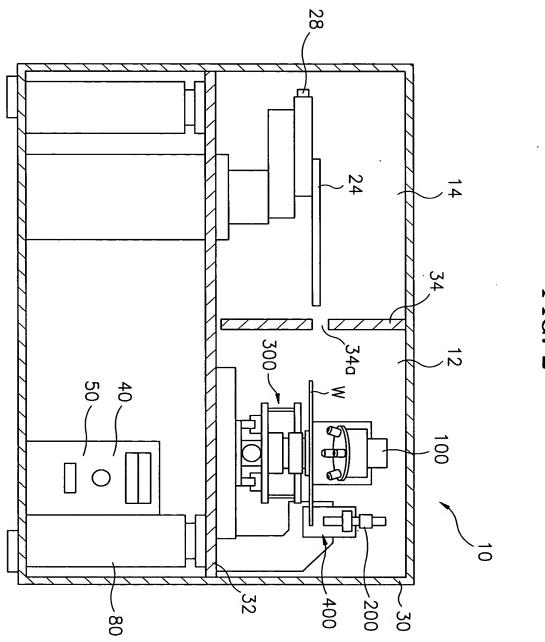
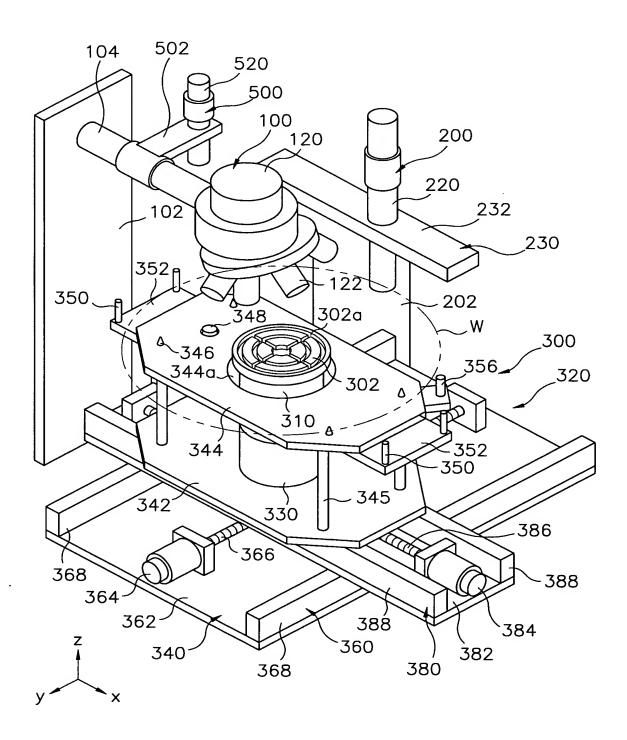


FIG. 2

FIG. 3



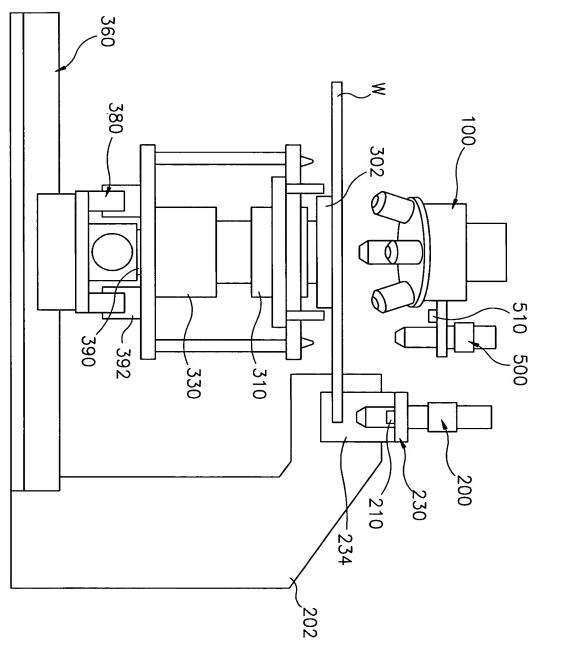
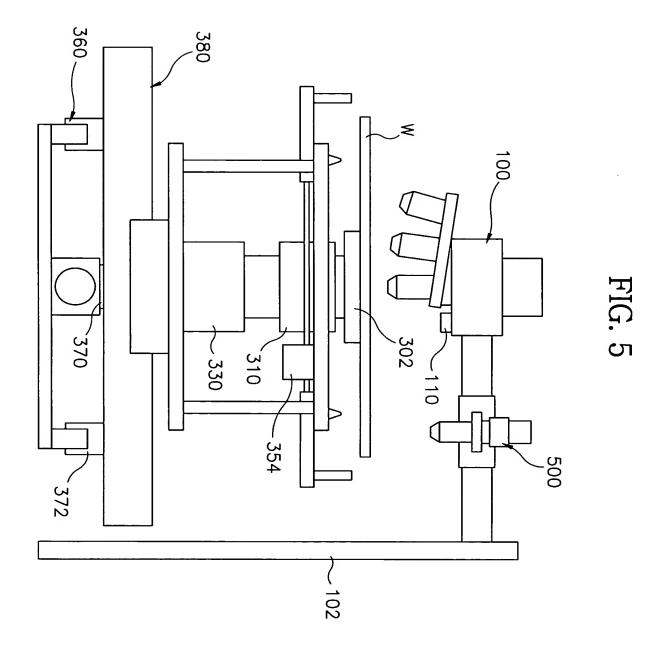


FIG. 4



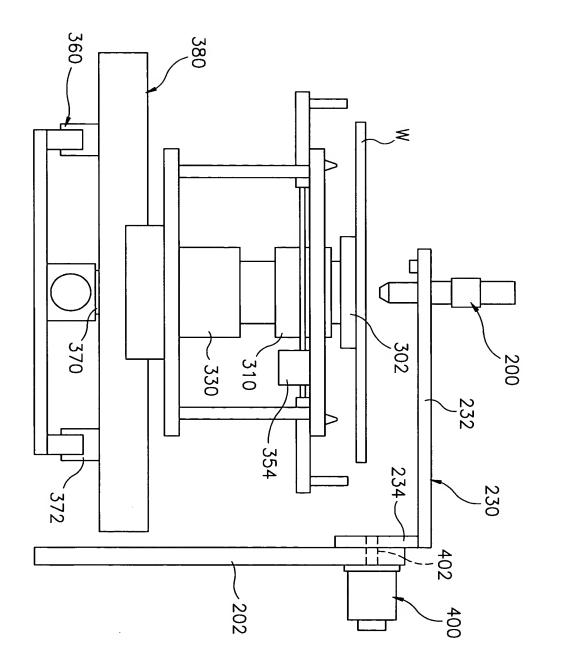


FIG. 6

356~ 348~ 28~ 26~ ACQUISITION UNIT FIRST IMAGE CONTAINER SENSOR MAPPING SENSOR **NOTCH SENSOR** WAFER SENSOR ~100 40~ CENTRAL PROCESSING UNIT IMAGE PROCESSING UNIT ACQUISITION UNIT 200 SECOND IMAGE ~50 FIFTH DRIVING UNIT FIRST DRIVING UNIT \~ 400 TRANSFER ROBOT HANDLING UNIT DISPLAY UNIT ACQUISITION UNIT THIRD IMAGE \sim 300 \sim 24 -354 ALIGNMENT PINS 350

FIG. 7

FIG. 8A

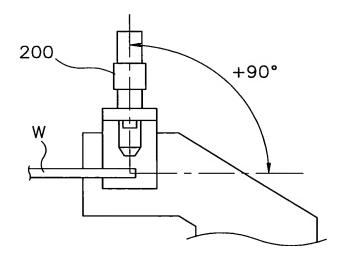


FIG. 8B

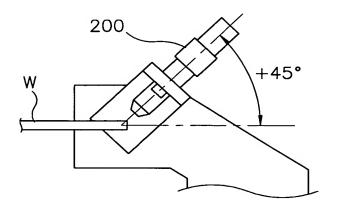


FIG. 8C

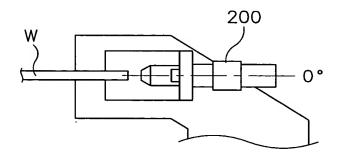


FIG. 8D

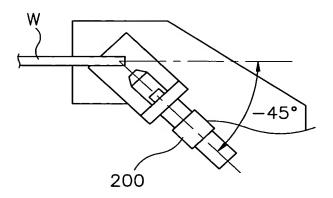


FIG. 8E

